

## EAST Search History

## EAST Search History (Prior Art)

Ref #	Hits	Search Query	DBs	Default Operator	Plurals	Time Stamp
L1	16	((JENS) near2 (FIEDLER)).INV.	US-PGPUB; USPAT; USOCR	OR	ON	2011/05/07 15:25
L2	50	((ANDREAS) near2 (MAYER)).INV.	US-PGPUB; USPAT; USOCR	OR	ON	2011/05/07 15:25
L3	12	((THOMAS) near2 (SCHWEIGER)).INV.	US-PGPUB; USPAT; USOCR	OR	ON	2011/05/07 15:25
L4	8	((MARTIN) near2 (STRATESTEFFEN)).INV.	US-PGPUB; USPAT; USOCR	OR	ON	2011/05/07 15:26
L5	65	(vertical and distance and linear and acceleration and speed).clm.	US-PGPUB; USPAT; USOCR	OR	ON	2011/05/07 15:27
L6	0	1 and 5	US-PGPUB; USPAT; USOCR	OR	ON	2011/05/07 15:27
L7	0	1 and 5	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2011/05/07 15:27
L8	0	2 and 5	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2011/05/07 15:27
L9	0	3 and 5	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2011/05/07 15:27
L10	0	4 and 5	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2011/05/07 15:27
L11	2	(vertical near2 distance) and (three near2 linear near3 acceleration) and (rotational near3 speed)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2011/05/07 15:29

S1	26	"1002709"	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/12/14 14:56
S2	2	"6000702".pn.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/12/14 15:00
S3	2	"6292759".pn.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/12/14 15:24
S4	55	("6292759").URPN.	USPAT	OR	ON	2009/12/14 15:26
S5	2	("20070067112").PN.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2009/12/14 15:28
S6	27779	(distance or height or displacement or movement) same chassis same (body or frame)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/12/14 16:13
S7	272782	acceleration and (speed or rotation\$2)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/12/14 16:14
S8	1394	S6 and S7	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/12/14 16:14
S9	348269	(rotation\$3 or speed) near3 (sensor or detect\$3)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/12/14 16:14

S10	227	S8 and S9	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/12/14 16:15
S11	390	(determin\$3 or calculat\$3 or estimat\$3) near3 (distance or height or displacement or movement) same chassis same (body or frame)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/12/14 16:15
S12	60	S11 and S10	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/12/14 16:16
S13	11	("6000702").URPN.	USPAT	OR	ON	2009/12/14 16:45
S14	7066198	(rotation\$3 or speed or roll or pitch)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/12/14 17:24
S15	280	(determin\$3 or calculat\$3 or estimat\$3) near3 (distance or height or displacement or movement) same chassis same (body or frame) and S14	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/12/14 17:24
S16	283156	(rotation\$3 or speed or roll or pitch) and (acclerometer or acceleration)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/12/14 17:25
S17	84	S15 and S16	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/12/14 17:25
S18	4098433	automatic\$3 near3 level\$3 or adjust\$3 or (height near2 adjust\$3)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/12/15 11:45

S19	4098433	automatic\$3 near3 level\$3 or adjust\$3 or (height near2 adjust\$3) and vehicle	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/12/15 11:46
S20	4098433	automatic\$3 near3 level\$3 or adjust\$3 or (height near2 adjust\$3) and vehicle and 701/clas.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/12/15 11:46
S21	4098433	(automatic\$3 near3 level\$3) or adjust\$3 or (height near2 adjust\$3) and vehicle and 701/clas.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/12/15 11:46
S22	23412	(automatic\$3 near3 level\$3) or (adjust\$3 or (height near2 adjust\$3)) and vehicle and 701/clas.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/12/15 11:47
S23	0	automatic\$3 near3 (level\$3 or adjust\$3 or (height near2 adjust\$3)) and vehicle and 701/clas.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/12/15 11:48
S24	93	automatic\$3 near3 (level\$3 or adjust\$3 or (height near2 adjust\$3)) and vehicl	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/12/15 11:48
S25	23097	accelerometer and (rotation \$3 or roll or pitch)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/12/15 11:49
S26	2	S24 and S25	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/12/15 11:49
S27	5	("3028175").URPN.	USPAT	OR	ON	2009/12/15 11:49

S28	7709	automatic\$3 near3 (level\$3 or adjust\$3 or (height near2 adjust\$3)) and vehicle	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/12/15 11:50
S29	222	S28 and S25	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/12/15 11:50
S30	2	"5569836".pn.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/12/15 12:16
S31	3	"5726886".pn.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/12/15 12:18
S32	1101894	(suspension)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/12/15 12:18
S33	266857	(suspension) and vehicle	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/12/15 12:19
S34	53721	accelerometers	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/12/15 12:19
S35	3127	S32 and S33 and S34	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/12/15 12:19
S36	2	"6000702".pn.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/12/15 14:58

S37	11	("6000702").URPN.	USPAT	OR	ON	2009/12/15 15:08
S38	2334002	(corner\$3 or inclin\$4) suspension and control and (level or height)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/12/15 15:24
S39	4705	accelerometer and pitch and roll	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/12/15 15:24
S40	2731381	vehicle	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/12/15 15:24
S41	1291	S38 and S39 and S40	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/12/15 15:24
S42	286013	lateral and vertical and longitud\$4	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/12/15 15:25
S43	648	S41 and S42	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/12/15 15:26
S44	516	S41 and S42 and suspension	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/12/15 15:26
S45	585	(calculat\$3 or estimat\$3 or determin\$3) near3 (height or level or distance or displacement or movement) and vehicle and suspension and accelerometer and pitch	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/12/15 15:40

S46	543	(calculat\$3 or estimat\$3 or determin\$3) near3 (height or level or distance or displacement or movement) and vehicle and suspension and accelerometer and pitch and roll	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/12/15 15:40
S47	523	(calculat\$3 or estimat\$3 or determin\$3) near3 (height or level or distance or displacement or movement) and vehicle and suspension and accelerometer and pitch and roll and sensors and suspension	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/12/15 15:40
S48	365	280/5.507.ccls.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/12/15 18:13
S49	81	280/5.507.ccls. and accelerometer	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/12/15 18:13
S50	14	("5475593").URPN.	USPAT	OR	ON	2009/12/15 22:11
S51	14	("5475593").URPN.	USPAT	OR	ON	2009/12/16 12:48
S52	3199	(accelerometers) and lateral and longitud\$4 and vertical	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/12/16 13:24
S53	964	(accelerometers) and lateral and longitud\$4 and vertical and suspension	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/12/16 13:25
S54	119	(accelerometers) and lateral and longitud\$4 and vertical and suspension and (rotation \$3 near3 sensors)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/12/16 13:25
S55	118	(accelerometers) and lateral and longitud\$4 and vertical and suspension and (rotation \$3 near3 sensors) and (level or height or distance or position)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/12/16 13:26

S56	78	(accelerometers) and lateral and longitudinal and vertical and suspension and (rotation near3 sensors) and ((level or height or distance or position) same suspension)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/12/16 13:26
S57	14	("5475593").URPN.	USPAT	OR	ON	2009/12/16 13:34
S58	5	("5864768").URPN.	USPAT	OR	ON	2009/12/16 13:43
S59	1	"5124938".pn.	USPAT	OR	ON	2009/12/16 13:52
S60	1	"6298292".pn.	USPAT	OR	ON	2009/12/16 13:58
S61	1	"5315295".pn.	USPAT	OR	ON	2009/12/16 14:14
S62	12	(determine near5 vertical near4 (movement or distance or displacement)) same chassis same (body or frame) and vehicle	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2010/10/12 10:28
S63	181	(determine near5 (movement or distance or displacement)) same chassis same (body or frame) and vehicle	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2010/10/12 10:30
S64	32	(acceleration and (speed or rotation or velocity)) and S63	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2010/10/12 10:31
S65	49	(determine near5 (movement or distance or displacement)) with chassis same (body or frame) and vehicle	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2010/10/12 15:20
S66	13	(acceleration and (speed or rotation or velocity)) and S65	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2010/10/12 15:20
S67	2	"6292759".pn.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2010/10/12 20:48



**EAST Search History (Interference)**

Ref #	Hits	Search Query	DBs	Default Operator	Plurals	Time Stamp
L12	1	(vertical near2 distance) and (three near2 linear near3 acceleration) and (rotational near3 speed)	USPAT; UPAD	OR	ON	2011/05/07 15:30

**5/ 7/ 2011 3:31:25 PM****C:\ Documents and Settings\ rmawari\ My Documents\ EAST\ Workspaces\ 10596368\_chasis.wsp**